

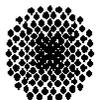
# FMM based solution of electrostatic and magnetostatic field problems on a PC-cluster

André Buchau

Wolfgang Hafla

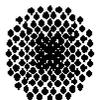
Friedemann Groh

Wolfgang M. Rucker



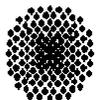
# Outline

- Introduction
- Vectorization
- Multithreading
- Multiprocessing
- Numerical examples
- Conclusions



## Numerical formulation

- Electrostatic field problems
- Boundary element method
- Indirect formulation based on charges
- Galerkin method
- Second order boundary elements
- Iterative solver GMRES with Jacobi preconditioner
- Fast multipole method

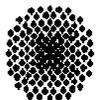


## Direct BEM formulation

- Electrostatics
- Steady current flow fields
- Green's theorem

$$c(\mathbf{r})u(\mathbf{r}) = \oint \frac{\partial u(\mathbf{r}')}{\partial n'} \frac{1}{|\mathbf{r} - \mathbf{r}'|} dA' - \oint u(\mathbf{r}') \frac{\partial}{\partial n'} \frac{1}{|\mathbf{r} - \mathbf{r}'|} dA'$$

- Dirichlet boundary conditions
- Neumann boundary conditions

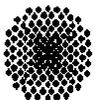


## Indirect BEM formulation

- Electrostatics
- Magnetostatics
- Charge densities

$$u(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \int_A \frac{\sigma(\mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|} dA'$$

- Dirichlet boundary conditions
- Neumann boundary conditions



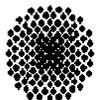
# Introduction

## Initial situation

- BEM with compressed matrix
- Very high compression rates (90 % to 99 %)
- Typical problem size: 10000 to 100000 unknowns
- Typical memory requirements: 100 MByte to 1 GByte
- Computing time for linear problems: up to a few hours
- Computing time for nonlinear problems: up to a few days

## Aim of parallelization

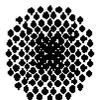
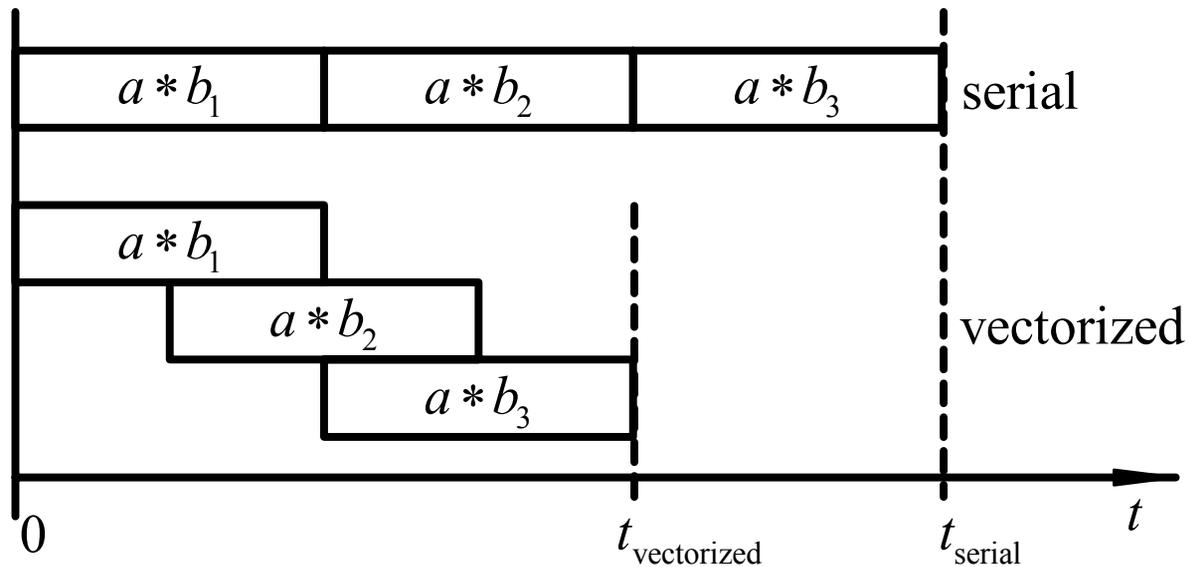
- Reduction of computing time



# Vectorization

## Properties

- Parallel execution of multiple instructions on a single CPU
- Hardware and compiler dependent
- Recommended for dense data structures

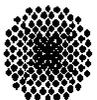


## Multipole transformations

- Classical multipole-to-local transformation
- Dense transformation matrix
- Processor optimized numerical libraries
- $O(L^4)$

$$L_n^m = \sum_{k=0}^L \sum_{l=-k}^k \frac{M_k^l j^{|m-l|-|m|-|l|} A_k^l A_n^m Y_{k+n}^{l-m}(\mu, \nu)}{(-1)^k \rho^{k+n+1} A_{n+k}^{l-m}}$$

$$\{L\} = [T_{M2L}] \{M\}$$



## Multipole transformations

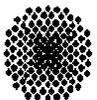
- Modified multipole-to-local transformation
- Sparse transformation matrices
- $O(L^3)$

$$[T] = [z_{\text{inv}}][y_{\text{inv}}][M2L_z][y][z]$$

$$M_n^m = M_n^m e^{jm\beta}$$

$$M_n^{m'} = \sum_{m=-n}^{-1} R(n, m, m', \alpha) (-1)^m (M_n^m)^* + \sum_{m=0}^n R(n, m, m', \alpha) M_n^m$$

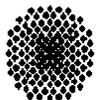
$$L_n^m = \sum_{k=m}^L M_k^m \frac{Y_{k+n}^0(0,0) (-1)^{k+m} (n+k)!}{\rho^{k+n+1} \sqrt{(k-m)!(k+m)!(n-m)!(n+m)!}}$$



# Vectorization

## Summary

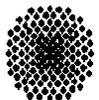
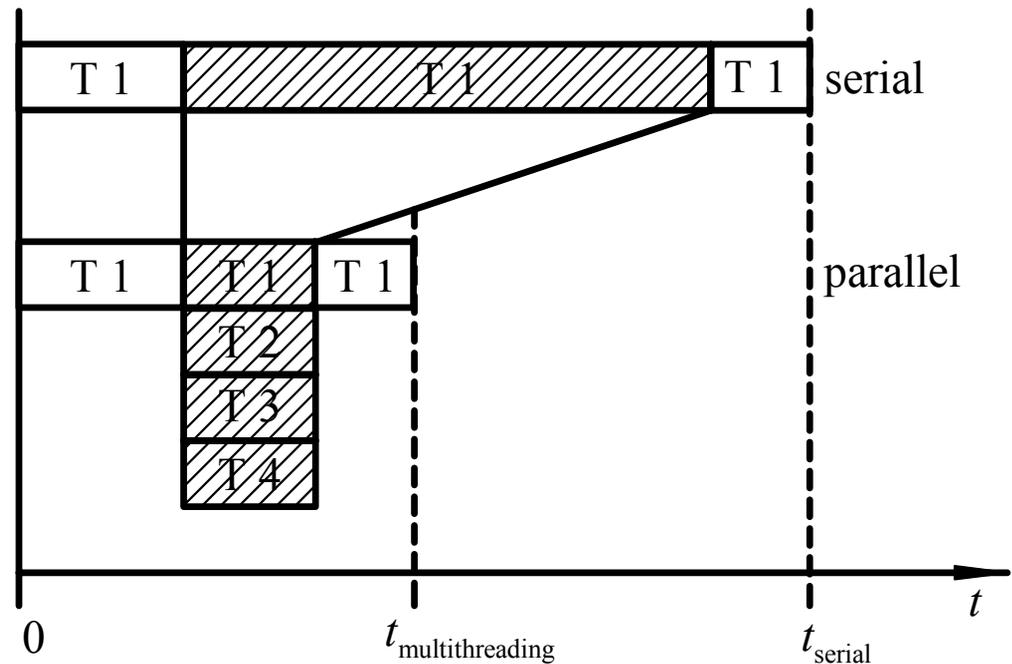
- Fast for dense operations
- Sparse operators are faster
- Use all special properties of the operators
- Reduce number of sub-operations



# Multithreading

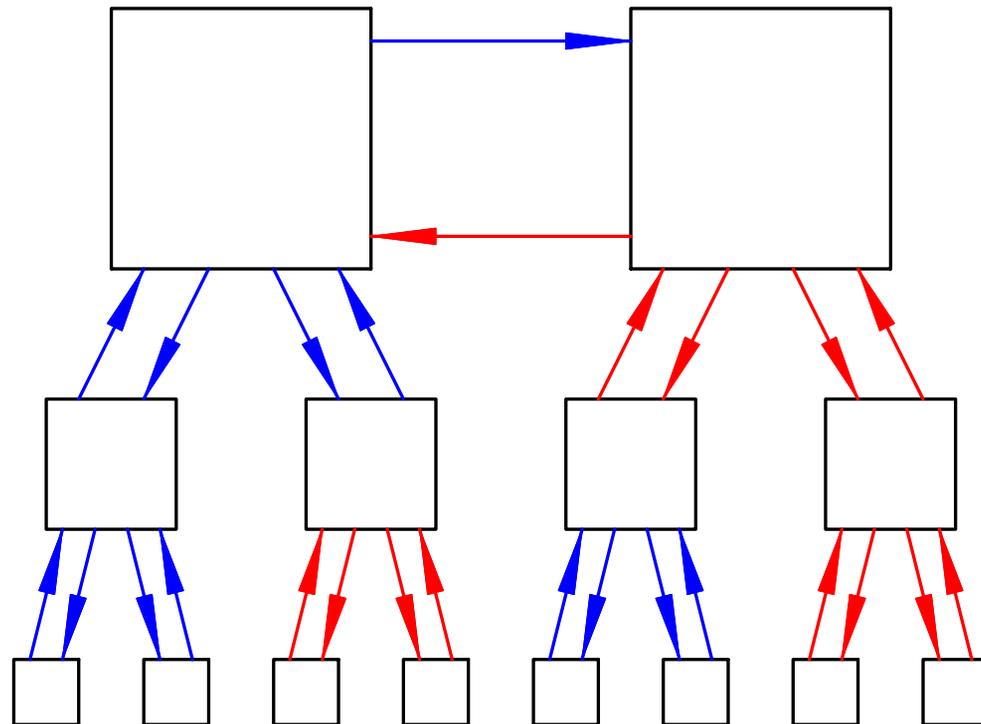
## Properties

- Easy to implement
- Only time consuming parts are parallelized
- Dynamic load distribution during runtime
- Shared memory access



## Multipole transformations

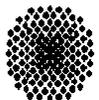
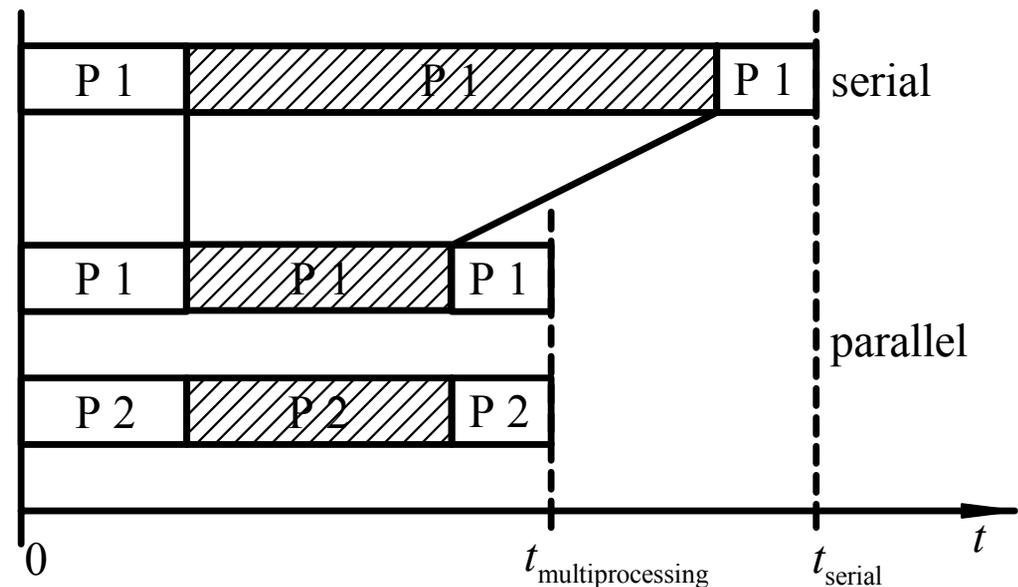
- Operations of the octree cubes can be computed independent of each other



# Multiprocessing

## Properties

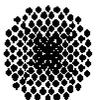
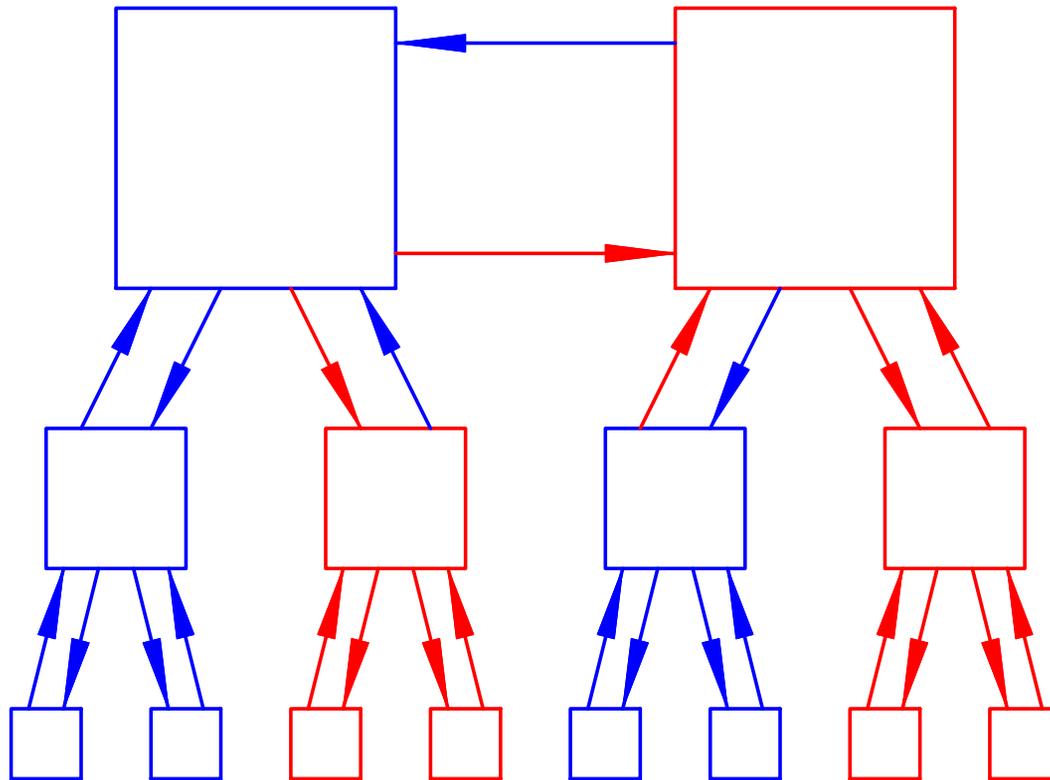
- Whole program runs in parallel
- Deterministic algorithm for load distribution
- Synchronization between processes



# Multithreading

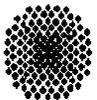
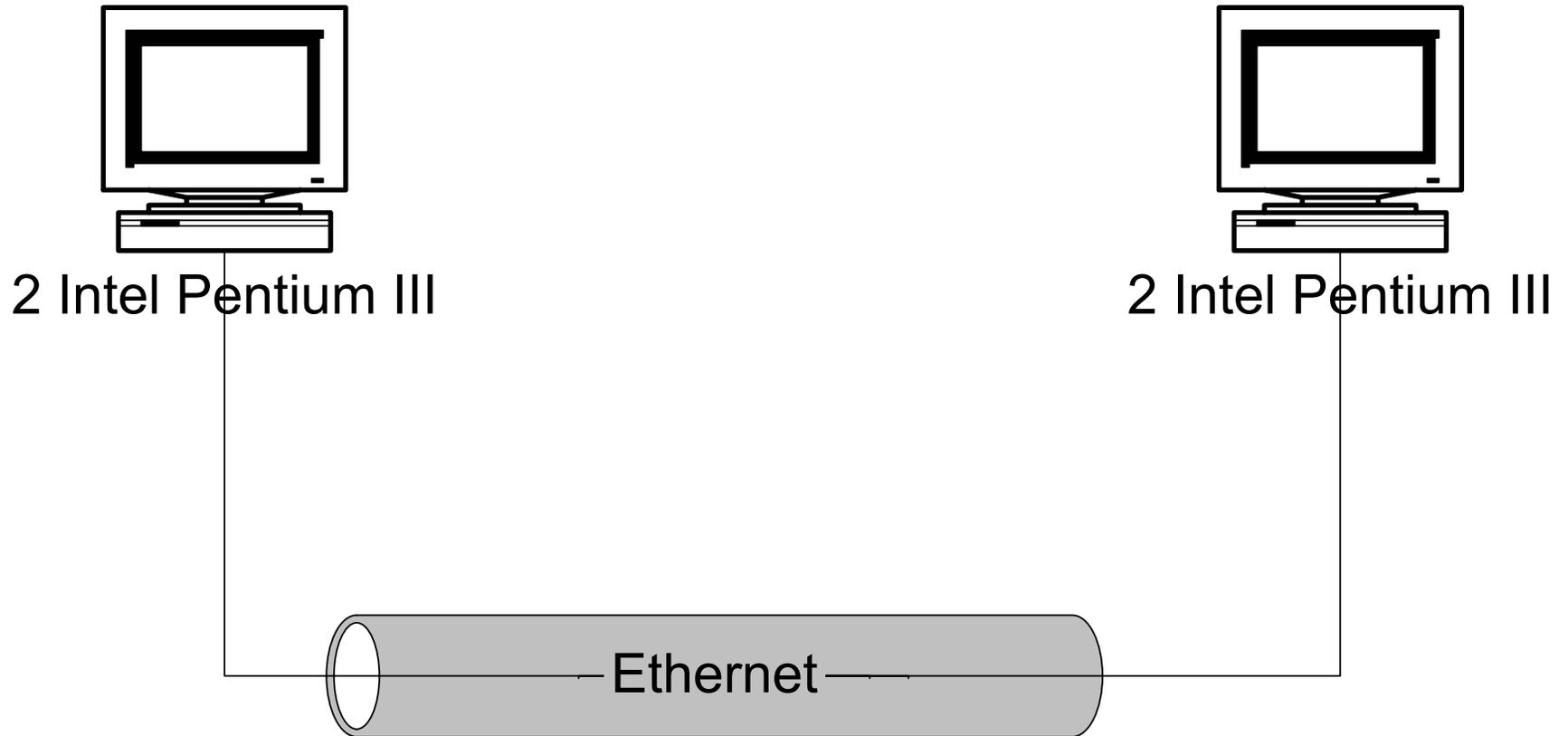
## Multipole transformations

- Data transfer between processes is necessary



# Numerical examples

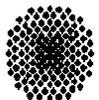
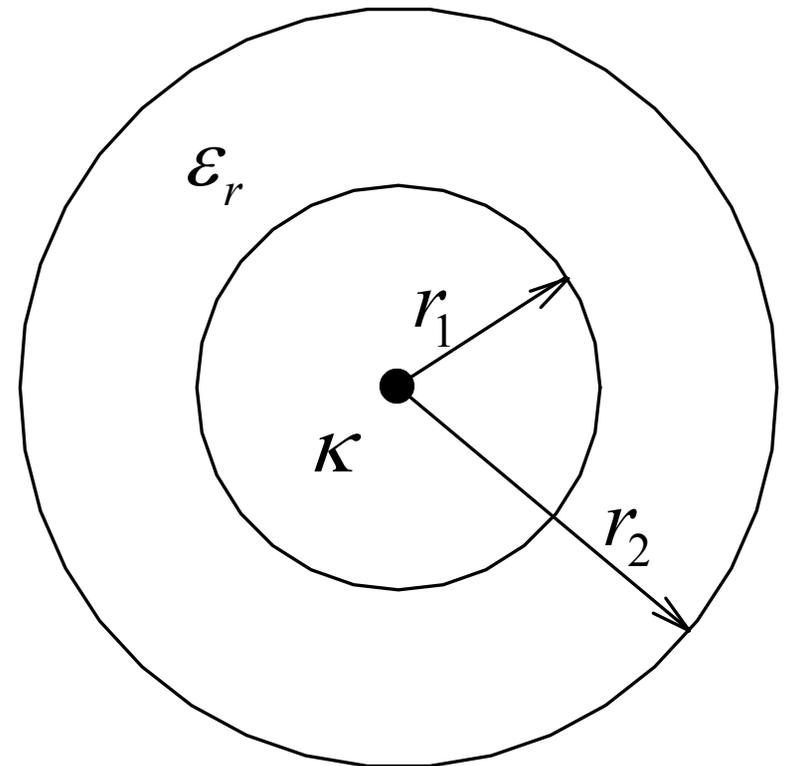
## Hardware



# Numerical examples

## Coated sphere

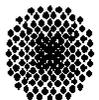
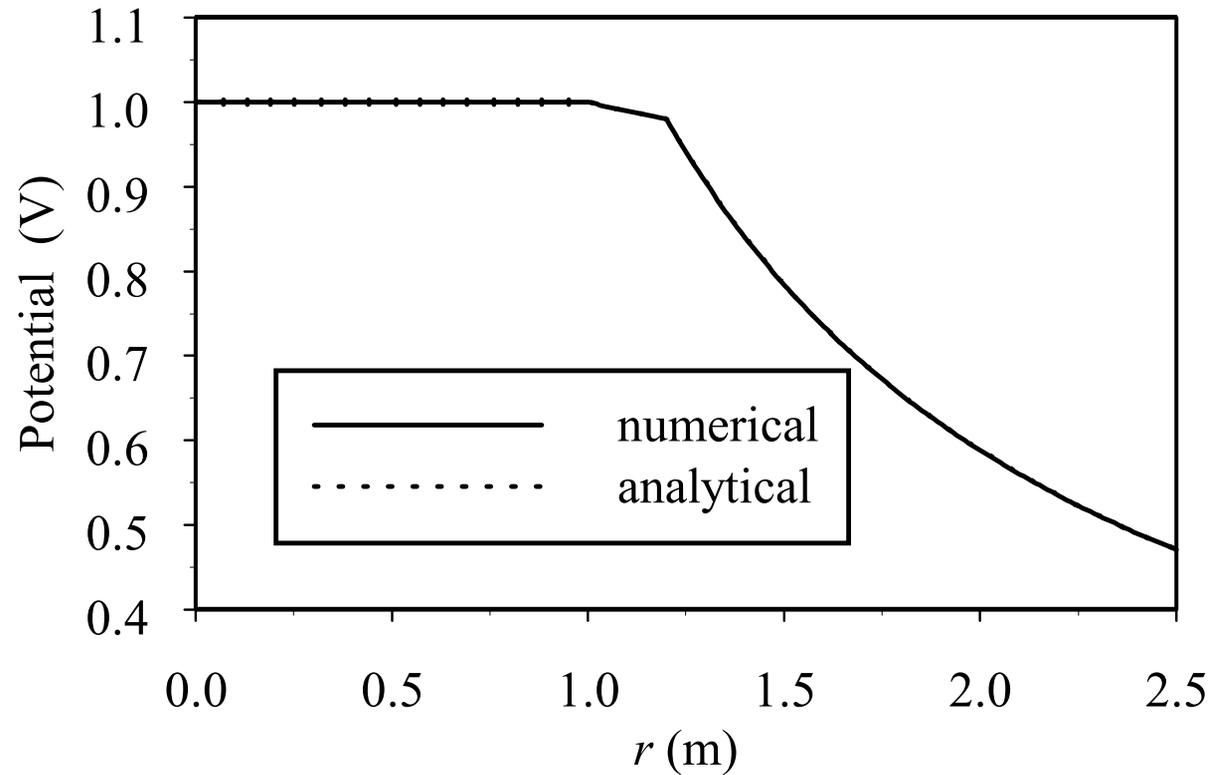
- 9892 second order quadrilateral elements
- 29680 unknowns
- 66 linear iteration steps
- 280 MByte
- Homogeneous mesh



# Numerical examples

## Coated sphere

- Potential at a radial line

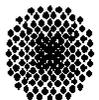


# Numerical examples

## Coated sphere

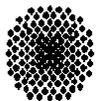
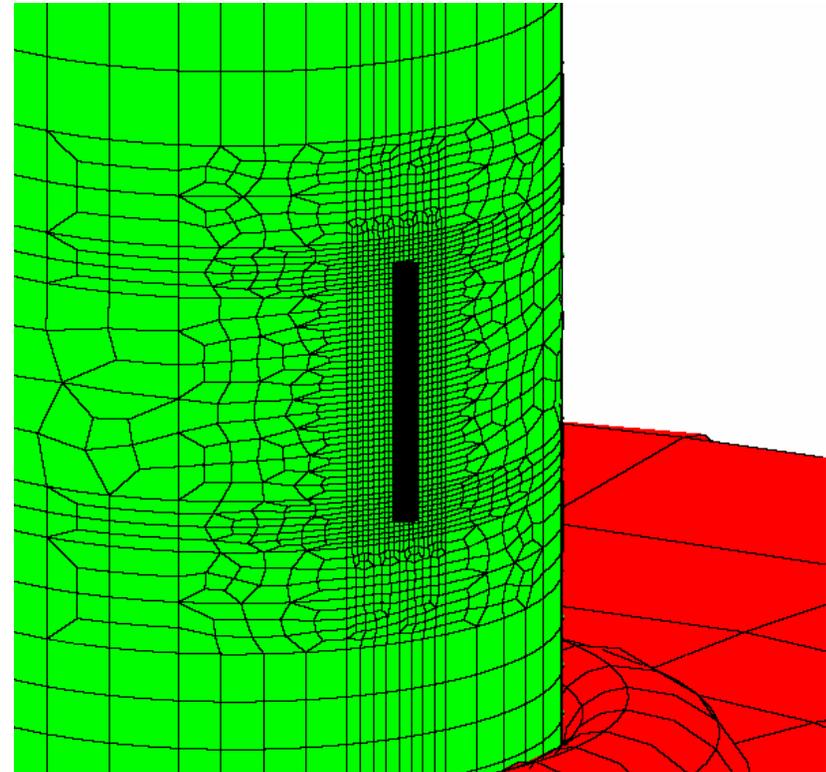
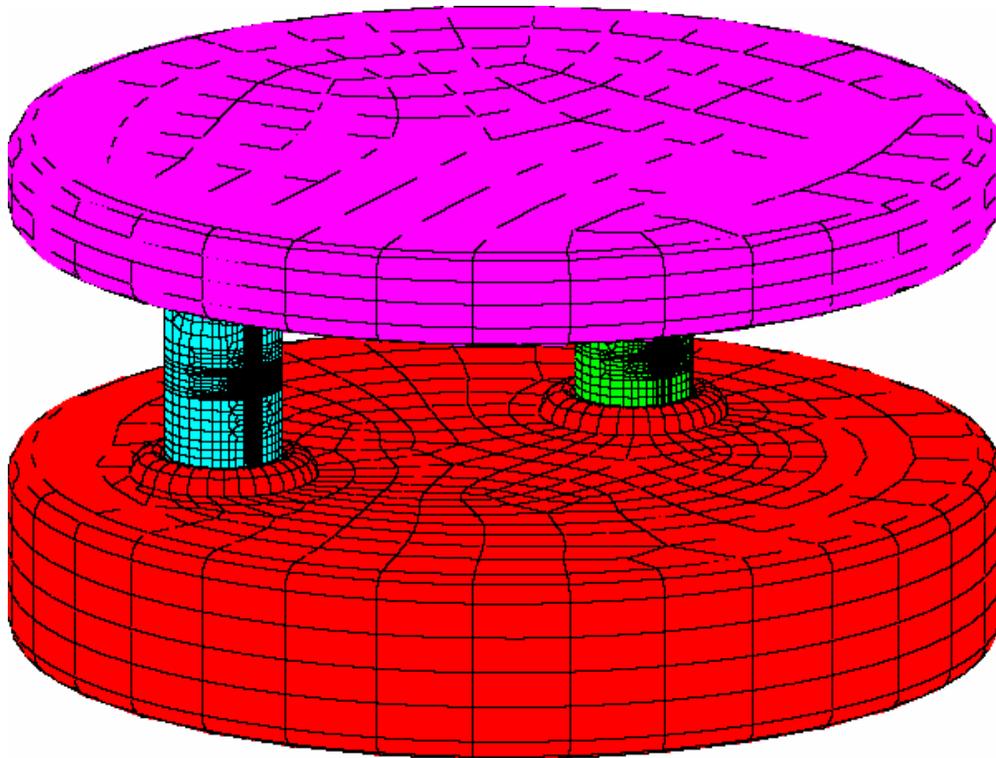
- Computing times

	Serial	OpenMP	OpenMP + MPI
Processes	1	1	2
Threads	1	2	2*2
Matrix assembly	2931 s	1466	
Reduction		50 %	
Solution linear equation system	3851 s	2387 s	1268 s
Reduction		38 %	67 % (38 % OpenMP, 47 % MPI)



# Numerical examples

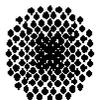
## Gas insulated high voltage system



# Numerical examples

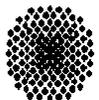
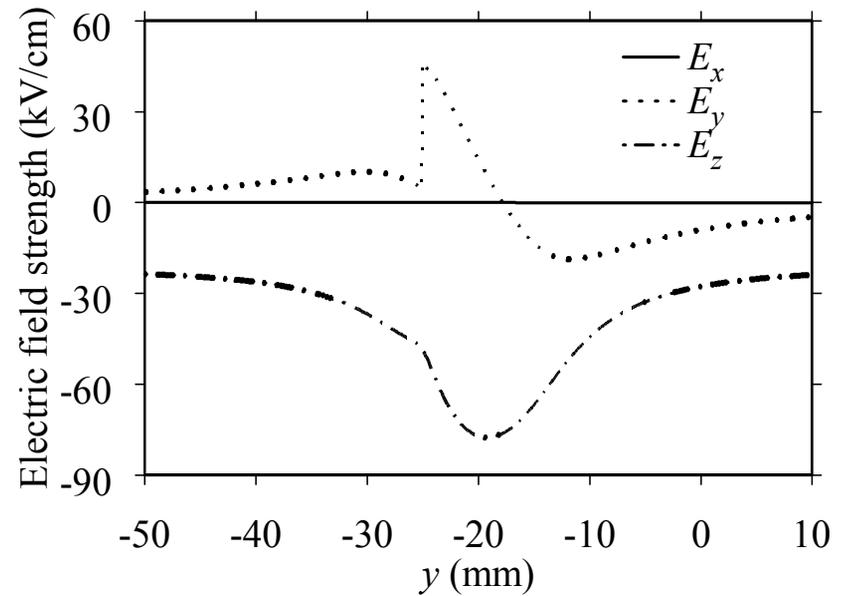
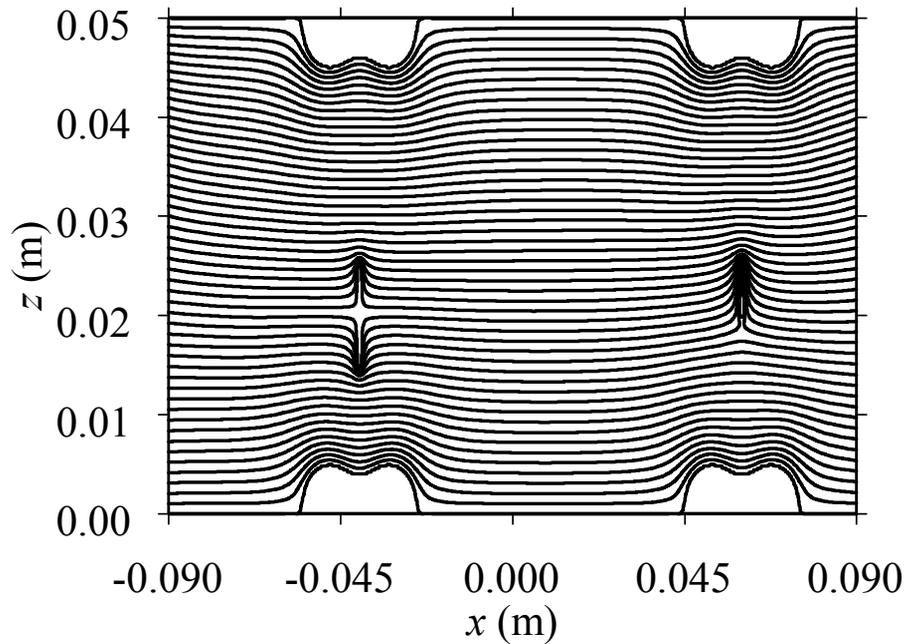
## Gas insulated high voltage system

- 9529 second order quadrilateral elements
- 28855 unknowns
- 178 linear iteration steps
- 305 MByte
- Problem oriented mesh



# Numerical examples

## Gas insulated high voltage system

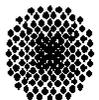


# Numerical examples

## Gas insulated high voltage system

- Computing times

	Serial	OpenMP	OpenMP + MPI	
Processes	1	1	2	
Threads	1	2	2*2	
Solution linear equation system	6730 s	4194 s	3360 s	2548 s
Reduction		38 %	50 % (19 % MPI)	62 % (39 % MPI)
Octree level			4	7



## Conclusions

- Compressed BEM matrices (fast multipole method)
- Vectorization, multithreading, multiprocessing
- Reduction of computing time
- Easy-to-implement approach
- Limits of numerical algorithms in combination with parallelization methods

